

Cognome	Nome	Total e	tema 1	tema 2	tema 3
ALHOMSI	MOHAMMAD	41	Artificial Intelligence methods and Robotic Assistance in Surgical Procedures - Univ. Modena e Reggio Emilia	Social robot assistant for intelligent health care - Univ. Palermo	Robotics for healthcare - Politecnico Torino
BAGLIERI	LORENZO	56	Robotics for healthcare - Politecnico Torino		
BERNABEI	MATTEO	54	Robotics enhanced by IoT and AI for healthcare 4.0 - Univ. Campus Bio-Medico Roma	Sensing for Medical Robotics - Scuola Sup. S. Anna Pisa	Robotics for healthcare - Politecnico Torino
BROGI	BERNARDO	53	Sensorimotor interfaces and control for human-robot collaboration - Univ. Siena	Sensorimotor interfaces and control for human-robot augmentation - Univ. Siena	
BRUNO	MARCO	51	Bio-inspired friction-based self-locomoting soft microbot - Univ. Salento		
CAROLEO	GIAMMARCO	54	Magnetic multi-robot system control - Scuola Sup. S. Anna Pisa	Sensing for Medical Robotics - Scuola Sup. S. Anna Pisa	Design and Operation Methodologies for Upper-Limb Exoskeletons - Univ. Calabria
CORE	LORENZO	48	Robotics for healthcare - Politecnico Torino	3D bioprinting of living materials - Univ. Genova	Advanced computer-vision techniques in body machine interfaces for rehabilitation and assistance of people with neurological diseases - MOVENDO-Univ. Genova
COSTA	DAVIDE	46	3D bioprinting of living materials - Univ. Genova		
FURNARI	GABRIELE	50	Artificial Intelligence methods and Robotic Assistance in Surgical Procedures - Univ. Modena e Reggio Emilia		
GIGOLA	MONICA	50	Legal issues of Robotics and Intelligent machine in medicine and healthcare - Univ. Genova		
HAMEED	RANA UMAIR	40	Social robot assistant for intelligent health care - Univ. Palermo	Diversity-Aware Social Robots for Education and Social Assistance - Scuola di Robotica-Univ. Genova	Legal issues of Robotics and Intelligent machine in medicine and healthcare - Univ. Genova

JABARI	MOHAMMAD	49	Artificial Intelligence methods and Robotic Assistance in Surgical Procedures - Univ. Modena e Reggio Emilia	Bio-inspired friction-based self-locomoting soft microbot - Univ. Salento	Robotics for healthcare - Politecnico Torino
KHALIL	MUHAMMAD ADNAN	46	Sensing for Medical Robotics - Scuola Sup. S. Anna Pisa	Design and Operation Methodologies for Upper-Limb Exoskeletons - Univ. Calabria	Magnetic multi-robot system control - Scuola Sup. S. Anna Pisa
LAGO	FRANCESCO	51	Design and Operation Methodologies for Upper-Limb Exoskeletons - Univ. Calabria		
LAGOMARSINO	BEATRICE	48	Advanced computer-vision techniques in body machine interfaces for rehabilitation and assistance of people with neurological diseases - MOVENDO-Univ. Genova	Virtual reality and robotic integration to assess human vestibular performance - MOVENDO-Univ. Genova	
MAHDIZADEH	OMID	40	Human-robot coexistence and interaction in robot-assisted medical procedures - Univ. Roma La Sapienza – Medlogix		
MISLEY	ELISA	46	Virtual reality and robotic integration to assess human vestibular performance - MOVENDO-Univ. Genova		
NICOTRA	EMANUELE	42	Human-robot coexistence and interaction in robot-assisted medical procedures - Univ. Roma La Sapienza – Medlogix		
POMPILIO	MICHELE	47	Sensorimotor interfaces and control for human-robot augmentation - Univ. Siena	Sensorimotor interfaces and control for human-robot collaboration - Univ. Siena	
PRESICCI	CLAUDIA	55	Study and development of a highly ergonomic wearable device for movement and posture assessment in rehabilitation, work, and sports - SWHARD-Univ. Genova	Virtual reality and robotic integration to assess human vestibular performance - MOVENDO-Univ. Genova	Advanced computer-vision techniques in body machine interfaces for rehabilitation and assistance of people with neurological diseases - MOVENDO-Univ. Genova
RAUF	MUHAMMAD ARSLAN	43	Advanced computer-vision techniques in	Motion and action	Legal issues of Robotics and

			body machine interfaces for rehabilitation and assistance of people with neurological diseases - MOVENDO-Univ. Genova	prediction for human-robot collaboration facilitated by body signals and context - Univ. Bolzano	Intelligent machine in medicine and healthcare - Univ. Genova
SAETTONE	LORENZA	54	Diversity-Aware Social Robots for Education and Social Assistance - Scuola di Robotica-Univ. Genova		
USAMA	SYED ALI	46	Motion and action prediction for human-robot collaboration facilitated by body signals and context - Univ. Bolzano	Robot assisted rehabilitation for older adults after strokes or traumatic events - Univ. Trento	Study and development of a highly ergonomic wearable device for movement and posture assessment in rehabilitation, work, and sports - SWHARD-Univ. Genova