



Corso: ROBOTICS AND INTELLIGENT MACHINES

Curriculum: INSPECTION AND MAINTENANCE OF INFRASTRUCTURES (CODICE 9349)

Oral interviews information

Date: 27 July 2022

Time: 9:00 CET (Rome Time)

Where: MS Teams

Link to the call:

https://teams.microsoft.com/l/meetup-join/19%3ameeting_MWQ5NzViZGIhNzhiMC00N2QwLWI4ZmMtMjg3OGEwNTE2ZTM4%40thread.v2/0?context=%7b%22Tid%22%3a%226cd36f83-1a02-442d-972f-2670cb5e9b1a%22%2c%22Oid%22%3a%2215bfa4e5-21e4-4134-80cb-8bde949c38d9%22%7d

Candidates admitted to the oral interview:

Surname	Name	Total (/60)	Research theme 1	Research theme 2	Research theme 3
ADORNI	MARCO	48	Robotic based underwater shallow water infrastructure inspection - Univ. Genova		
BETTA	ZOE	55	Autonomous quadrupeds to improve public infrastructures resilience - Univ. Genova		
INFANTONE	GIUSEPPE	49	Autonomous quadrupeds to improve public infrastructures resilience - Univ. Genova	Human-centric, interactive, personal robotics - Univ. Pisa	

KHANMEH	JURI	48	Robotic based underwater shallow water infrastructure inspection - Univ. Genova	Development and experimentation of a Reconfigurable Underwater Vehicle for Inspection, Free-floating Intervention and Survey Tasks - Univ. Firenze	
LISO	ADRIANO	53	Deep learning models for quality control and anomaly detection in Industry 4.0 - CNR STIIMA		
PAGNANELLI	GIULIA	48	Human-centric, interactive, personal robotics - Univ. Pisa		
REZA	TAHERI	46	Deep learning models for quality control and anomaly detection in Industry 4.0 - CNR STIIMA	Autonomous quadrupeds to improve public infrastructures resilience - Univ. Genova	Human-centric, interactive, personal robotics - Univ. Pisa
RIZVI	SYED MUHAMMAD RAZA	42	Autonomous quadrupeds to improve public infrastructures resilience - Univ. Genova	Human-centric, interactive, personal robotics - Univ. Pisa	Development and experimentation of a Reconfigurable Underwater Vehicle for Inspection, Free-floating Intervention and Survey Tasks - Univ. Firenze
VANGI	MIRCO	52	Development and experimentation of a Reconfigurable Underwater Vehicle for Inspection, Free-floating Intervention and Survey Tasks - Univ. Firenze		