I-RIM
Italian Institute of Robotics and Intelligent Machines

Ph.D COURSE *ROBOTICS AND INTELLIGENT MACHINES* CURRICULUM *HOSTILE AND UNSTRUCTURED ENVIRONMENTS*

(CODE 9347)

XXXVIII CICLO

Following the assessment of qualifications (Step 1), the below candidates:

ABDELMOTTALEB	YARA ALAAELDIN ABDELAZIZ	47	Detection and tracking of obstacles for autonomous marine vehicles – Univ. Genova	AI methods for Robots in Unstructured Environments – Italian Inst. of Technology	
ADORNI	MARCO	47	Detection and tracking of obstacles for autonomous marine vehicles – Univ. Genova		
CARADONNA	DANIELE	55	Soft Robotics for Human Cooperation and Rehabilitation (II) - Italian Inst. of Technology		
CHEN	ZIXI	47	AI methods for Robots in Unstructured Environments – Italian Inst. of Technology	Distributed tactile sensing for elephant-trunk inspired soft manipulators - Italian Inst. of Technology	Soft Robotics for Human Cooperation and Rehabilitation (II) - Italian Inst. of Technology
GUTTIKONDA	SURESH	45	AI methods for Robots in Unstructured Environments – Italian Inst. of Technology	Traversability for Mobile Robots in Hostile and Unstructured Environments – Univ. Catania	
HAKDIYEN	AYDIN	46	Social perception in unstructured environments – Univ. Milano Bicocca		

HAMEED	RANA UMAIR	40	AI methods for Robots in Unstructured Environments – Italian Inst. of Technology	Social perception in unstructured environments – Univ. Milano Bicocca	Traversability for Mobile Robots in Hostile and Unstructured Environments – Univ. Catania
MARTINI	MICHELE	51	Soft Robotics for Human Cooperation and Rehabilitation (II) - Italian Inst. of Technology	Soft growing and adaptable robots for exploration of extreme environments – Italian Inst. of Technology	Distributed tactile sensing for elephant-trunk inspired soft manipulators - Italian Inst. of Technology
MILAZZO	GIUSEPPE	55	Soft Robotics for Human Cooperation and Rehabilitation (II) - Italian Inst. of Technology		
MORADI	MOHAMMAD	49	Traversability for Mobile Robots in Hostile and Unstructured Environments – Univ. Catania		
PAGNANELLI	GIULIA	53	Soft Robotics for Human Cooperation and Rehabilitation (II) - Italian Inst. of Technology		
PAROSI	RICCARDO	48	Detection and tracking of obstacles for autonomous marine vehicles – Univ. Genova	AI methods for Robots in Unstructured Environments – Italian Inst. of Technology	
PRIVITERA	LUIGI	47	Distributed tactile sensing for elephant-trunk inspired soft manipulators - Italian Inst. of Technology	Detection and tracking of obstacles for autonomous marine vehicles – Univ. Genova	Soft Robotics for Human Cooperation and Rehabilitation (II) - Italian Inst. of Technology
PURANAM	VENKATA RITHWICK	52	Soft growing and adaptable robots for exploration of extreme environments – Italian Inst. of Technology		
SIMONINI	GIORGIO	51	Soft Robotics for Human Cooperation and Rehabilitation (II) - Italian Inst. of Technology		
SONCINI	JACOPO CIRO	47	Soft growing and adaptable robots		

			for exploration of extreme environments – Italian Inst. of Technology		
TOLOMEI	SIMONE	42	AI methods for Robots in Unstructured Environments – Italian Inst. of Technology		

are invited to the online interview (Step 2 - oral examination) on MONDAY 25 JULY at 9.30 (Central European Summer Time) through the Google Meet call: https://meet.google.com/xkz-ivri-qnz Candidates will be required to exhibit a valid identification document prior to starting the interview.