



**Ph.D COURSE *ROBOTICS AND INTELLIGENT MACHINES*
CURRICULUM *HOSTILE AND UNSTRUCTURED*
*ENVIRONMENTS***

(CODE 9553)

XXXVIII CICLO

Following the assessment of qualifications (Step 1), the below candidates:

	Score /60	Research Theme 1	Research Theme 2	Research Theme 3
LI ZHICHAO	51	SCENE PERCEPTION WITH FRAME-BASED AND EVENT-DRIVEN VISUAL SENSORS		
GASPERINI DAMIANO	48	PERCEPTION AND SEMANTICS FOR ROBOT LOCO-MANIPULATION	MACHINE LEARNING FOR MOBILE MANIPULATION IN DYNAMIC ENVIRONMENT	SCENE PERCEPTION WITH FRAME-BASED AND EVENT-DRIVEN VISUAL SENSORS
ADORNI MARCO	47	UNDERWATER OBSTACLE DETECTION AND AVOIDANCE WITH SONAR DATA		
PEYGHAMBAR ZADEH SEYED MOHAMMAD MOEIN	43	SCENE PERCEPTION WITH FRAME-BASED AND EVENT-DRIVEN VISUAL SENSORS	UNDERWATER OBSTACLE DETECTION AND AVOIDANCE WITH SONAR DATA	PERCEPTION AND SEMANTICS FOR ROBOT LOCO-MANIPULATION
PELLEGRINO ERIKA	42	SCENE PERCEPTION WITH FRAME-BASED AND EVENT-DRIVEN VISUAL SENSORS		

are invited to the online interview (Step 2 - oral examination) on **THURSDAY 22 DECEMBER** at 9.00 (Central European Summer Time) through the Teams call: <https://teams.microsoft.com/l/meetup->

join/19%3ameeting_OGRiNmIxYjMtMzRkMS00YmI5LTgwYzUtZGRiY
zMzOTM4NWNh%40thread.v2/0?context=%7b%22Tid%22%3a%226cd
36f83-1a02-442d-972f-
2670cb5e9b1a%22%2c%22Oid%22%3a%22cf8fbac8-92a4-423d-b3a0-
e21a6eebb098%22%7d

If you have problems connecting, please feel free to contact Prof. Sgorbissa
at +39 320 4218938

Candidates will be required to exhibit a valid identification document prior
to starting the interview.