



**Ph.D COURSE *ROBOTICS AND INTELLIGENT MACHINES***  
**CURRICULUM *HOSTILE AND UNSTRUCTURED***  
***ENVIRONMENTS***  
**(CODE 9553)**  
**XXXVIII CICLO**

**IMPORTANT NOTICE**

The official rankings will be published within January 24<sup>th</sup> on the University Portal: Dottorati di ricerca | unige.it

The enrollments will start on January 25<sup>th</sup> as detailed in the call (see Dottorati di ricerca | unige.it)

**FINAL RANKINGS**

[Machine learning for mobile manipulation in dynamic environment - Istituto Italiano di Tecnologia](#)

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[Scene perception with frame-based and event-driven visual sensors - Istituto Italiano di Tecnologia](#)

1. LI ZHICHAO

Underwater Obstacle Detection and Avoidance with Sonar Data – Università degli Studi di Genova

1. ADORNI MARCO

Mobility Control of Legged and Wheeled Robots – Istituto Italiano di Tecnologia

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Perception and semantics for Robot Loco-manipulation – Istituto Italiano di Tecnologia

1. GASPERINI DAMIANO

Human-Robot Collaborative Control for Legged/Wheeled Mobile platforms – Istituto Italiano di Tecnologia

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