



Ph.D COURSE ROBOTICS AND INTELLIGENT MACHINES CURRICULUM HOSTILE AND UNSTRUCTURED ENVIRONMENTS (CODICE 9926), XXXIX CICLO

Following the assessment of qualifications (Step 1), the below candidates:

	Totale /60	Tema 1	Tema 2	Tema 3
ADEKOYA OMOTOYE SHAMSUDEEN	51	AUGMENTED REALITY STRATEGIES FOR TEAMS OF ROBOTS – UNIVERSITY OF GENOVA	ROBOT NAVIGATION ANYWHERE: MOVING AROUND AUTONOMOUSLY IN HOSTILE AND UNSTRUCTURED ENVIRONMENTS – UNIVERSITY OF GENOVA	
ADHAMI ROMINA	47	SOFT ROBOTICS TECHNOLOGIES FOR MARINE ENVIRONMENT – ISTITUTO ITALIANO DI TECNOLOGIA		
BELOUSOV VLADISLAV	44	AUTONOMOUS LOCOMANIPULATION PLANNING FOR LOGISTICS MOBILE ROBOTS – ISTITUTO ITALIANO DI TECNOLOGIA	AUGMENTED REALITY STRATEGIES FOR TEAMS OF ROBOTS – UNIVERSITY OF GENOVA	ROBOT NAVIGATION ANYWHERE: MOVING AROUND AUTONOMOUSLY IN HOSTILE AND UNSTRUCTURED ENVIRONMENTS – UNIVERSITY OF GENOVA
BOUANANE MOHAMED SADEK	44	ONLINE NEUROMORPHIC PERCEPTION AND ACTUATION FOR ROBOTS – ITALIAN INSTITUTE OF TECHNOLOGY	NEUROMORPHIC DISTRIBUTED INTELLIGENCE FOR SOFT ROBOTS – DESIGN OF NEUROMORPHIC CIRCUITS ON FLEXIBLE SUBSTRATES FOR SENSING AND COMPUTATION –	NEUROMORPHIC DISTRIBUTED INTELLIGENCE FOR SOFT ROBOTS – COMPUTATION WITH SPIKING NEURAL NETWORKS FOR HAPTIC PERCEPTION

			ITALIAN INSTITUTE OF TECHNOLOGY	AND CLOSED LOOP CONTROL OF SOFT ROBOTS – ITALIAN INSTITUTE OF TECHNOLOGY
CHATZITHANOS PARASKEVAS	45	AUTONOMOUS LOCOMANIPULATION PLANNING FOR LOGISTICS MOBILE ROBOTS – ISTITUTO ITALIANO DI TECNOLOGIA	ROBOT NAVIGATION ANYWHERE: MOVING AROUND AUTONOMOUSLY IN HOSTILE AND UNSTRUCTURED ENVIRONMENTS – UNIVERSITY OF GENOVA	AUGMENTED REALITY STRATEGIES FOR TEAMS OF ROBOTS – UNIVERSITY OF GENOVA
DAI RUI	50	AUTONOMOUS LOCOMANIPULATION PLANNING FOR LOGISTICS MOBILE ROBOTS – ISTITUTO ITALIANO DI TECNOLOGIA	SOFT ROBOTICS FOR HUMAN COOPERATION AND REHABILITATION – ISTITUTO ITALIANO DI TECNOLOGIA	SOFT ROBOTICS TECHNOLOGIES FOR MARINE ENVIRONMENT – ISTITUTO ITALIANO DI TECNOLOGIA
GANDOLFI GABRIELE	44	ONLINE NEUROMORPHIC PERCEPTION AND ACTUATION FOR ROBOTS – ITALIAN INSTITUTE OF TECHNOLOGY	NEUROMORPHIC DISTRIBUTED INTELLIGENCE FOR SOFT ROBOTS – COMPUTATION WITH SPIKING NEURAL NETWORKS FOR HAPTIC PERCEPTION AND CLOSED LOOP CONTROL OF SOFT ROBOTS – ITALIAN INSTITUTE OF TECHNOLOGY	EASY-TO-USE MODELS AND TOOLS FOR SCALABLE VERIFICATION OF ROBOTICS DELIBERATION - UNIVERSITA' DI GENOVA/BOSCH
GOMIERO SARA	41	PLANNING AND CONTROL TECHNIQUES FOR HIGH-LEVEL AUTONOMY OF ROBOTS – UNIVERSITY OF PISA	MULTI-MODAL OBJECT GRASPING AND MANIPULATION – ISTITUTO ITALIANO DI TECNOLOGIA	HUMAN-AWARE ROBOT NAVIGATION – ISTITUTO ITALIANO DI TECNOLOGIA
GORI PIETRO	44	PLANNING AND CONTROL TECHNIQUES FOR HIGH-LEVEL AUTONOMY OF ROBOTS – UNIVERSITY OF PISA		
IOTTI FRANCESCO	45	PLANNING AND CONTROL TECHNIQUES FOR HIGH-LEVEL AUTONOMY OF ROBOTS – UNIVERSITY OF PISA		
KHATAVKAR ROHAN	43	SOFT ROBOTICS FOR HUMAN COOPERATION AND REHABILITATION – ISTITUTO ITALIANO DI TECNOLOGIA	SOFT ROBOTICS TECHNOLOGIES FOR MARINE ENVIRONMENT – ISTITUTO ITALIANO DI TECNOLOGIA	

MOSLEMI MOHAMMADMAHDI	48	ROBOT NAVIGATION ANYWHERE: MOVING AROUND AUTONOMOUSLY IN HOSTILE AND UNSTRUCTURED ENVIRONMENTS – UNIVERSITY OF GENOVA	AUTONOMOUS LOCOMANIPULATION PLANNING FOR LOGISTICS MOBILE ROBOTS – ISTITUTO ITALIANO DI TECNOLOGIA	PLANNING AND CONTROL TECHNIQUES FOR HIGH-LEVEL AUTONOMY OF ROBOTS – UNIVERSITY OF PISA
PALMAS MATTEO	51	EASY-TO-USE MODELS AND TOOLS FOR SCALABLE VERIFICATION OF ROBOTICS DELIBERATION - UNIVERSITA' DI GENOVA/BOSCH		
PUANG EN YEN	55	MULTI-MODAL OBJECT GRASPING AND MANIPULATION – ISTITUTO ITALIANO DI TECNOLOGIA		
TRUNIN PETR	47	DISTRIBUTED TACTILE SENSING FOR ELEPHANT-TRUNK INSPIRED SOFT MANIPULATORS – ITALIAN INSTITUTE OF TECHNOLOGY		
WANG SHENQI WANG	42	ONLINE NEUROMORPHIC PERCEPTION AND ACTUATION FOR ROBOTS – ITALIAN INSTITUTE OF TECHNOLOGY	NEUROMORPHIC DISTRIBUTED INTELLIGENCE FOR SOFT ROBOTS – COMPUTATION WITH SPIKING NEURAL NETWORKS FOR HAPTIC PERCEPTION AND CLOSED LOOP CONTROL OF SOFT ROBOTS – ITALIAN INSTITUTE OF TECHNOLOGY	NEUROMORPHIC DISTRIBUTED INTELLIGENCE FOR SOFT ROBOTS – DESIGN OF NEUROMORPHIC CIRCUITS ON FLEXIBLE SUBSTRATES FOR SENSING AND COMPUTATION – ITALIAN INSTITUTE OF TECHNOLOGY
WANG YANG	40	ONLINE NEUROMORPHIC PERCEPTION AND ACTUATION FOR ROBOTS – ITALIAN INSTITUTE OF TECHNOLOGY	SOFT ROBOTICS FOR HUMAN COOPERATION AND REHABILITATION – ISTITUTO ITALIANO DI TECNOLOGIA	SOFT ROBOTICS TECHNOLOGIES FOR MARINE ENVIRONMENT – ISTITUTO ITALIANO DI TECNOLOGIA
YOUSEFI ALI	49	ROBOT NAVIGATION ANYWHERE: MOVING AROUND AUTONOMOUSLY IN HOSTILE AND UNSTRUCTURED ENVIRONMENTS –	AUTONOMOUS LOCOMANIPULATION PLANNING FOR LOGISTICS MOBILE ROBOTS – ISTITUTO ITALIANO DI TECNOLOGIA	

		UNIVERSITY OF GENOVA		
ZAWAR UL HASSAN MUHAMMAD	40	SOFT ROBOTICS FOR HUMAN COOPERATION AND REHABILITATION – ISTITUTO ITALIANO DI TECNOLOGIA	PLANNING AND CONTROL TECHNIQUES FOR HIGH-LEVEL AUTONOMY OF ROBOTS – UNIVERSITY OF PISA	ONLINE NEUROMORPHIC PERCEPTION AND ACTUATION FOR ROBOTS – ITALIAN INSTITUTE OF TECHNOLOGY
ZUPPETTI RICCARDO	44	ROBOT NAVIGATION ANYWHERE: MOVING AROUND AUTONOMOUSLY IN HOSTILE AND UNSTRUCTURED ENVIRONMENTS – UNIVERSITY OF GENOVA		

are invited to the online interview (Step 2 - oral examination) on WEDNESDAY 26th July at 9.00 (Central European Summer Time) through the Teams call:

https://teams.microsoft.com/l/meetup-join/19%3ameeting_MTZiNjE2ZTktMmVkNi00YjA2LWFkYTgtZjE5ODk0MDVjZTNh%40thread.v2/0?context=%7b%22Tid%22%3a%226cd36f83-1a02-442d-972f-2670cb5e9b1a%22%2c%22Oid%22%3a%22cf8fbac8-92a4-423d-b3a0-e21a6eebb098%22%7d

If you have problems connecting, please feel free to contact Prof. Scaradozzi (Università Politecnica delle Marche) at +39 071 220 4383, d.scaradozzi@univpm.it

Candidates will be required to exhibit a valid identification document prior to starting the interview.