This is a preliminary list of classes for the 2024-2025 academic year. We are publishing it now as some classes will begin in November 2024, allowing students to plan ahead. This document will be updated periodically. If you wish to attend a class, please contact the designated reference persons as soon as possible.

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Consiglio Nazionale delle Ricerche (CNR-ISTC and CNR-STIIMA)

Reference person: Andrea Orlandini <andrea.orlandini@istc.cnr.it>, Nicola Pedrocchi <nicola.pedrocchi@stiima.cnr.it>

Name	Teacher	Ore	Class description	Availab	Time of the	Langu	Final	Level
				le	year (please	age	evaluation	
				online	check)			
Automated Planning	Andrea	10	The course presents Artificial Intelligence	yes	June 2025	English	yes	BASIC
	Orlandini,		automated planning. It introduces models		(ask for			
	Alessandro		and resolution approaches for both		details)			
	Umbrico,		"classic" and temporal planning. Different					
	andrea.orlandi		methodologies for the synthesis of action					
	ni@istc.cnr.it,		plans and their execution will be presented,					
	umbrico.aless		as well as applications in relation to the					
	andro@gmail.		control of autonomous robots.					
	com							

Istituto Italiano di Tecnologia (IIT)

Reference person: Lorenzo Natale <Lorenzo.Natale@iit.it>

Name	Teacher	Ore	Class description	Availa ble online	Time of the year (please check)	Langua ge	Final evaluation	Level
Open Science and Research Data Management (OS&RDM)	Anna Maria Pastorini, Valentina Pasquale, anna.maria.past orini@unige.it, valentina.pasqua le@iit.it	10	This training module for PhD Students aims to introduce early-career researchers to the principles of scholarly communication, Open Science and Research Data Management. Students will gain a better understanding of the available research einfrastructures, tools, and services for Open Access publishing, Research Data Management and FAIR Data. Students will also learn the importance and the transformative potential of Open Science practices in research, especially to improve reproducibility and increase research integrity. They will learn what means to make data FAIR, as required by many funders, including the European Commission, and how to draft a data management plan. Finally, they will have the chance to practice on common tools for Research Data Management, like Data Stewardship Wizard, Zenodo, and Dataverse.	yes	Feb 2025 (ask for details)	English	yes	CROSSUOVER
Modern C++	Marco Accame, Valentina Gaggero, Nicolò Genesio, marco.accame@ iit.it, valentina.gagger o@iit.it	30	The students will learn the new syntax and philosophy of Modern C++ (releases C++11, -14, -17, -20) with hands on the code at every lesson.	yes	May-Jun 2025	English	yes	BASIC

Mechanical Drawing Fundamentals	Diego Torazza, diego.torazza@ii t.it	18	This course provides an introduction to Mechanical Technical Drawing with mention to manufacturing techniques. The aim of the course is to give a base knowledge in understanding and preparing mechanical technical drawings, so there is no need of prior background of mechanical drawing. Mechanical drawing is the main way to communicate design need to technicians, workshops, suppliers. A base knowledge of rules and methods helps the researcher, even if not directly engaged in mechanical design, to better contribute to interdisciplinary team working when involved in the design of experimental setups, scientific devices, and the writing/understanding of technical specifications.	No	Jan 2025	English	yes	BASIC
ComputerAided Design	Diego Torazza, diego.torazza@ii t.it	12	The aim of the course is to gain and apply knowledge of 3D CAD concepts and techniques by using high-end CAD systems (PTC Creo).	No	Jun 2025	English	yes	ADVANCED
Perceptual systems	Monica Gori, Alessia Tonelli, monica,gori@iit.i t, alessia.tonelli@ii t.it	12	From birth, we interact with the world through our senses. How the brain process and transform sensory signals into perceptual outputs is one of the main questions in the field of experimental psychology. The goal of the course is to present the perceptual from the anatomical, physiological, and functional points of view. A particular focus will be on how physical stimuli are transduced into sensory signals by our peripheral sensory apparatus in a hierarchy organize complex behaviour. In the last part of the course, these topics will be described in relation with cross-sensory interaction and multisensory integration in the adult and the developing brain. Students will learn how the functioning of the main sensory systems, i.e. vision, audition, touch, small and taste. Moreover, it will be explain the	yes	March 2025	English	yes	ADVANCED

			process of multisensory integration and					
			cross-modal interaction.					
Robotic Virtual Prototyping Design	Ferdinando Cannella, Mariapaola D'Imperio (TA: Gabriele Marchello), ferdinando.cann ella@iit.it	18	The aim of the Robotic Virtual Prototyping Design course is to give the basic knowledge about the Finite Element Analysis (FEA) and Multi-Body Simulations (MBS) applied to the robotics. These computational techniques predict the behavior of physical systems: joined together permit to study the dynamics taking in account the body flexibility, the control and optimization. It will be introduced mainly applied to the mechanical field, in particular to the robotic anthropomorphic arm. The student gets 6 credits if he/she attends the entire course and accomplishes the final project.	yes	May-Jun 2025	English	yes	CROSSOVER
Mechatronics and AI	Ferdinando Canella, Gabriele Marchello, ferdinando.cann ella@iit.it	18	The aim of the Mechatronics and Artificial Intelligence (AI) course is to give the basic knowledge about AI and Deep Learning (DL) applied to mechatronics. The course will provide the students with an overview of AI, DL and the possible applications, and will focus in the last lectures on reinforcement learning (RL) techniques. AI, DL and especially RL can be adopted to control the behavior of mechatronic systems acting in complex environment, and solving tasks too hard to be tackled with traditional approaches. The student gets 6 credits if they attend the entire course and passes the final project.	yes	Jun 2025	English	yes	ADVANCED

Politecnico di Torino (Polito)

Reference person: Giuseppe Quaglia <giuseppe.quaglia@polito.it>, Carmen Visconte <carmen.visconte@polito.it>

Name	Teacher	Ore	Class description	Availa ble online	Time of the year (please check)	Langua ge	Final evaluation	Level
Advanced scientific programming in matlab	Paolo Bardella, paolo.bardel la@polito.it	30	The course aims to provide advanced skills in scientific programming, and to teach sound methodologies for the development of reliable, optimized and maintainable codes. A basic knowledge of MATLAB and the C language represents a prerequisite of this course. During this course, many common methods used in Scientific Computing will be presented, with particular attention to the most recent programming techniques in MATLAB. At the end of the course, the student will have expanded his/her knowledge of MATLAB and will be able to choose the best approach for the solution of numerical problem he/she will face.	yes	Jan/Feb 2025	English	yes	ADVANCED
Development and management of data-acquisition systems	Alessio Carullo, alessio.carul lo@polito.it	25	The course, open to all those who perform experimental activity and do not have specific knowledge on analogue and digital electronic circuits, is conceived to analyze and study multi-channel data-acquisition systems, to develop the know-how required for choosing and configuring the components of the measuring chain according to the requirements. Sensors and circuitry commonly employed in the industrial field to adapt the sensor output signals to the analogue-to-digital converter will be studied. Furthermore, the performance of different architectures of data-acquisition systems will be analyzed	No	Jun 2025	English	yes	ADVANCED

			(dedicated systems, data-acquisition boards for personal computer, microcontroller based boards), also revising the most common development environments. Eventually, guide lines for the estimation of the expected uncertainty will be provided. Laboratory experiments will be arranged in order to develop and analyze some case studies.					
Machine learning for pattern recognition	Sandro Cumani, sandro.cum ani@polito.i t	20	This course gives a broad yet rigorous introduction to machine learning and statistical pattern recognition. It focuses on supervised generative and discriminative learning models, analyzing some important topics such as model architectures, training and evaluation techniques. The course will compare different models and classification approaches on the popular MNIST digit recognition dataset. It will also discuss about the applications of the proposed machine learning approaches to image, speech, and speaker recognition. Students will be asked to apply the acquired knowledge to develop their own classification system using labeled training and evaluation data provided during the course. Each system will then be evaluated on another unlabeled and previously unseen data set.	yes	Jun 2025	English	yes	ADVANCED
Principles, materials and applications of robotics in biomedicine	Alberto Arezzo	20	Robotic technologies for minimally invasive surgery and diagnosis is the focus of this course. Clinical needs in extra-, endo- and trans-luminal access approaches are identified. Various engineering solutions are discussed and their evolution over time is presented and justified. Discussed topics, technologies and methodologies include, but are not limited to: history of surgical robots, commercial surgical robots, research robotic systems, gastrointestinal robots, advances in soft robots fabrication, sensing and actuation, cancer detection robots, perceptual human-robot interfaces,	yes	Feb 2025	English	yes	ADVANCED

			data- and AI-driven operating theatres, etc					
			with the major scientific players worldwide					
			in their respective fields of competence.					
Research design and methodology	Federico Bella, federico.bell a@polito.it	11	This course is intended to explain to PhD students how high-quality scientific research can be carried out during the three years of the doctorate course. The lessons will address the path that goes from the assignment of the research project to the literature analysis, from the design of research activities to the interaction with other scientists, from the production of tangible results to the analysis of the metrics commonly adopted to assess the quality of research and researchers. The overall aim of the course is that of making PhD students aware of	No	Mar 2025	English	yes	CROSSOVER
			what a PhD is and which is the spirit					
			required to face it.					
Facing the scientific publishing world	Federico Bella, federico.bell a@polito.it	12	This course is intended to introduce the world of scientific publishing to PhD students starting their academic career. The lessons will address the main pillars of this sector, from the fundamentals of journals organization to the rational construction of an article, from the peerreview process to the evaluation of research and researchers through internationally recognized metrics. The main aim of this course is to make PhD students aware of the international scientific publishing system.	No	Mar 2025	English	yes	CROSSOVER
Research communication and relationships with companies and organizations	Diana Caterina Nada Massai diana.massa i@polito.it,	10	The objective of the course is to provide the PhD students the essential tools for improving their skills in communicating the scientific research to the business world, particularly focusing on the relationships with start-ups, PMIs, large companies and public organizations. By attending the course, the PhD students will increase their communication skills for interacting with professionals from the business world, with the final aims of promoting the	No	March 2025	English	yes	CROSSOVER

			collaboration between academia and industry and supporting the technology transfer. A dedicated webpage will be available with news, alerts, materials, links, and useful information for the course attendance and work progress. The course is limited in number to 50 participants: registration is required in the manner indicated by the Nucleo Dottorato di ricerca.					
Writing research proposal and EU projects		10	The figure of the researcher has become more complex. In addition to knowing how to do research and translate the results of their efforts into scientific papers, the researcher must possess project management skills that include knowing how to monitor European, national, and regional funding opportunities, as well as how to write project proposals in response to such calls. The ongoing European programming 2021-2027 offers considerable opportunities for the researcher who aspires to obtain more funds to finance its own research. Although only an introduction, this course aims to help PhD candidates develop certain project management skills, i.e., the search of funding opportunities, the analysis of the essential elements and requirements of the calls, and the preparation of a project proposal.	No	Nov 2024	English	yes	CROSSOVER
Innovation management	Francesca Montagna, francesca.m ontagna@p olito.it	8	Innovation Management is nowadays a recognized discipline that concerns scientific knowledge and professional skills. In the current economic environment, the transfer of technological development results into products and services, which must be both profitable for businesses and useful to society, is in fact not immediate and requires special capabilities. These required capabilities and skills are transversal and common to the different expressions of technology, as well as to	No	Nov 2024	English	yes	CROSSOVER

			various disciplines and industrial sectors. In this sense, they constitute a fundamental					
			professional and cultural background for Engineers, Architects and Designers.					
			Innovation management covers both					
			strategic and technical-operational					
			decisions, as well as the definition of those					
			core competences for the management					
			and support of innovation processes and					
			product and service development. The					
			course mainly aims at blending a					
			managerial perspective, so to make the					
			doctoral student capable of understanding					
			the innovation process, to the more					
			traditional perspectives from the specific					
			design disciplines. It also provides					
			indications on the main current research					
			questions and on the work being carried					
			out by researchers in the field. The course					
			is based on lessons, with wide use of cases					
			drawn from experience and empirical					
			research and case studies where students					
			are required to analyse information in a					
			quantitative manner. At the end of the					
			course, students will have acquired a					
			concrete ability to analyze and manage					
			business and design decisions related to					
			technological innovation in both strategic					
			and operational terms. They also acquire					
			full mastery of approaches for the management of R&D and innovative					
			processes, product and service					
			development.					
Intellectual Property Rights	Federico	6	This course aims to provide students with	No	Mar 2025	English	yes	CROSSOVER
and Innovation	Caviggioli,		fundamental knowledge on the Intellectual				'	
	federico.cav		Property Rights (IPRs) that are available to					
	iggioli@polit		protect creativity and innovation. The					
	o.it		definitions and the main characteristics of					
			patents, trademarks, copyrights, designs,					
			creative commons, etc. will be examined.					
			Students will be introduced to some of the					
			sources of IPR data which can be searched					
			to perform preliminary prior art analyses.					

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			In particular, the course will focus on					
			patent data as a source of information					
			which could help the researchers in					
			developing new technical developments					
			from a scientific perspective and improve					
			their understanding of a technological field.					
			The definition of such a technology					
			landscape can be also useful for supporting					
			the communication of technology trends					
			and their socio-economic impact, in					
			particular for project funding.					
Creativity and idea	Buiatti	20	The main objective of this course is the	No	Mar 2025	English	yes	CROSSOVER
generation techniques	Eleonora,		generation and development of new and					
	eleonora.bui		creative ideas by specific techniques and					
	atti@polito.i		psychological models. The first part of the					
	t		course will be dedicated to theoretical					
			aspects related to the main mechanisms of					
			the human mind involved in mostly					
			automated and recursive processes: mental					
			models, heuristics and automatisms. The					
			sensory aspects of human perception will					
			also be studied to show how the strategic					
			actions are possible, during the meta-					
			project and the design phase, in order to					
			specifically convey particular characteristics					
			of any artifact, interface or environment. At					
			the same time, during the course, the main					
			Tools through which it is possible to					
			measure perceptual aspects will be shown					
			(Eyetracking and SounBe). Finally, the					
			second part of the course will see students					
			to apply creative models using innovative					
			device based on the holographic principle.					
			The main idea will be to create a prototype					
			of innovative learning, taking as a specimen					
			a course devoted to physical topics					
			(Structural mechanics aspects), in order to					
			apply the communicative 10etworks10ic					
			language to the students. The learners will					
			generate the images, the 3D contents they					
			will traduce them in holograms and they					
			will project with the teacher a learning					
			-					
			path for an innovative pilot course.]	1		1	1

Scuola Superiore Sant'Anna (SSSA)

Referenti: Arianna Menciassi <arianna.menciassi@santannapisa.it> e Calogero Oddo <Calogero.Oddo@santannapisa.it> The courses can be BASIC (to establish cultural foundations), ADVANCED (advanced study of specific topics), CROSSOVER (on interdisciplinary subjects).

Name	Teacher	Ore	Class description	Availab le online	Time of the year (please check)	Langu age	Final evaluation	Level
Neuromorphic Computing	Calogero Maria Oddo, Calogero.Od do@santann apisa.it	20	The course will explore computational and physical models that emulate the neural dynamics and the efficiency of biological neurons of peripheral and central nervous system.	Yes	Dec 2024/Jan 2025	English	yes	CROSSOVER
Graphical programming for measurement, test, and control systems in bioengineering	Calogero Maria Oddo, Calogero.Od do@santann apisa.it	20	The main competences developed will be fundamentals and technical abilities of graphical programming for biomedical engineering. The main software used will be LabVIEW (Core 1 module), with the aim to address the following detailed topics: introduction to graphical programming; navigating the graphical programming environment; what is graphical programming; project explorer; parts of a Virtual Instrument (VI); front panel; block diagram; searching for controls, Vis, and functions; selecting a tool; dataflow; building simple Vis; troubleshooting and debugging Vis; implementing a VI; data types; documenting code; while and for loops; timing a VI and data feedback in loops; plotting data; case structures; developing modular applications; data structures: arrays and clusters; managing file and hardware resources; introduction to data exchange via UDP; Euler method for discrete fixed-step solution of differential equations and graphical implementation; hands on examples with graphical programming.	Yes	Oct 2025	English	yes	BASIC

Neural Networks and Deep Learning: Theoretical Foundations	Giorgio Buttazzo, giorgio.butta zzo@santan napisa.it	20	The objective of the course is to provide key concepts and methodologies to understand neural networks, explaining how to use them for pattern recognition, image classification, signal prediction, system identification, and adaptive control. Topic will include fully connected networks, unsupervised learning, selforganizing maps, clustering algorithms, autoencoders, reinforcement learning, supervised learning, multi-layer networks, Backpropagation, radial basis function networks, recurrent networks, attention mechanism.	Yes	Starts on 7th January 2025	English	yes	BASIC
Neural Network and Deep Learning: Deep Networks	Giorgio Buttazzo, giorgio.butta zzo@santan napisa.it	20	This module presents the foundations for understanding deep neural networks and deep learning algorithms. Topics include convolutional networks for classification, detection and segmentation, deep reinforcement learning, generative adversarial networks and transformers.	Yes	Starts of 4 th February 2025	Englis h	Si	CROSSOVER
Neural Network and Deep Learning: Advanced Topics	Giorgio Buttazzo, giorgio.butta zzo@santan napisa.it	20	This module presents recent techniques proposed to improve neural models and overcome their limitations. Topics include model compression, semi-supervised learning, anchor-free object detection, neural object tracking, adversarial attacks and defense methods, methods for explainable AI and anomaly detection.	Yes	Starts of 4 th February 2025	Englis h	Si	ADVANCED
Neural Networks and Deep Learning: Implementation Issues	Giorgio Buttazzo, giorgio.butta zzo@santan napisa.it	30	The objective of the course is to present practical and implementation issues useful to deploy neural networks on a variety of embedded platforms using different languages and development environments. Topics include implementing neural networks from	Yes	Starts on 1 st April 2025	Englis h	yes	ADVANCED

			scratch in C, TensorFlow, Keras, and PyTorch. Neural 13etworks for autonomous driving. Model optimization for embedded platforms. Accelerating deep networks on GPGPUs and FPGA.					
Fundamentals of Surgical and Interventional Robotics	Arianna Menciassi, arianna.men ciassi@santa nnapisa.it	10	The course will be focused on methodologies and guidelines related to robotic technologies for minimally invasive therapy, diagnosis and surgery. Lectures will introduce different solutions for targeted therapies both minimally invasive and no invasive, e.g. which exploit external generators of therapeutic actions. At the end of the course the student will be able to identify the most appropriate targeting/therapeutic solutions for the different human body districts, at different scales, and for different pathologies. Competence to be acquired along the course: • the design principles behind robotic technology for MIS; • different technologies and paradigms for autonomous, teleoperated, hand held robots for minimally invasive surgery; • actuation technologies for robotic tools for minimally invasive surgery.	Yes	Feb-Apr 2025	English	yes	CROSSOVER

Università di Firenze (UNIFI)

Reference person: Benedetto Allotta <benedetto.allotta@unifi.it>

Name	Teacher	Ore	Class description	Availab le online	Time of the year (please check)	Langu age	Final evaluation	Level
Current Trends in Marine Robotics	Alessandro Ridolfi, alessandro.ri dolfi@unifi.it	3	The course describe the state of the art of research in Marine Robotics and suggests hot fields of investigation	yes	Autumn/Wint er 2024	English	sì	BASIC
Maneuverability Analysis of Underwater Vehicles	Benedetto Allotta, benedetto.al lotta@unifi.i t	3	The course describes how to evaluate the dynamic maneuverability of underwater vehicles starting from the vehicle dynamic model and the thruster model	yes	Spring/Summ er 2025	English	sì	ADVANCED

Università degli studi di Genova (UNIGE)

Reference person: Giorgio Cannata <giorgio.cannata@unige.it>, Antonio Sgorbissa <antonio.sgorbissa@unige.it>

To be defined

Università degli studi di Milano Bicocca (UNIBM)

Reference person: Domenico Giorgio Sorrenti <domenico.sorrenti@unimib.it>, Dimitri Ognibene <dimitri.ognibene@unimib.it>

To be defined

Università degli Studi di Napoli Federico II (UNINA)

Reference person: Silvia Rossi <silrossi@unina.it>

Name	Teacher	Ore	Class description	Availab le online	Time of the year (please check)	Langu age	Final evaluation	Level
Social Robotics	Silvia Rossi, Alessandra Rossi, silrossi@uni na.it	16	In this module, students will learn the key aspects of designing and developing robots' behaviours that are accepted and familiar to people. Particular attention will be given to robotics applications and scenarios where robots are expected to have close interactions with people and support therapists and caregivers. Students will be provided with an overview of the multidisciplinary aspects to consider in order to design a human-robot interaction (HRI) by discussing and learning aspects and techniques from different relevant fields, such as robotics, computer science, engineering, psychology, and artificial intelligence (AI). Students will learn how to design and conduct a HRI study, and how to choose subjective and objective measures to evaluate the interaction with the robot, and people's perception of the robot's behaviours and their effect on users. Students will also be exposed to different robots, such as Pepper and Furhat, that are used in human-centred scenarios, such as assistive robots in private homes, care facilities and hospitals, robotic companions in home environments, and robots in rehabilitation centers.	yes	Spring/Summ er 2025	English	yes	CROSSOVER

Università degli Studi di Padova (UNIPD)

Reference person: Giulio Rosati <giulio.rosati@unipd.it>

Name	Teacher	Ore	Class description	Availab le online	Time of the year (please check)	Langu age	Final evaluation	Level
Python programming for Data Science and Engineering	Stefano Tortora, stefano.tort ora@unipd.i t	20	Aim: Python is an easy-to-learn and powerful high-level language and it is becoming more and more popular for scientific applications such as machine learning, statistics, manipulating and transforming data, but also computer vision and robotics. The first objective of the course is to become familiar with Python syntax, environments and basic libraries. Secondly, the learner will be guided in performing basic inferential data analyses and introduced to the application of common machine learning algorithms. Topics: 1- Introduction to the Python Programming Language	yes	Mar/Apr 2025	English	yes	BASIC

 Matplotlib: MATLAB-style scientific visualization 		
 Scikit-learn: Basics of Machine Learning in Python 		

Università degli Studi di Palermo (UNIPA)

Reference person: Adriano Fagiolini <adriano.fagiolini@unipa.it>

Name	Teacher	Ore	Class description	Availab le online	Time of the year (please check)	Langu age	Final evaluation	Level
Robot Consciousness	Antonio Chella	12	Robot Consciousness is a seminal field placed at the crossing between technical disciplines (AI, Robotics, Computer Science and Engineering), theoretical disciplines (Philosophy of Mind, Linguistic, Logic), and empirical disciplines (Psychology and Neuroscience). Robot consciousness focuses on attempts to apply the methods of AI, robotics and computer science to various ways of understanding consciousness and to examine the possible role of consciousness in robot systems. The course will present the current state of research and will discuss both the theoretical foundations and the experimental result of the emerging field of robot consciousness.	yes	Mar/Apr 2025	Englis h	yes	CROSSOVER

Sapienza Università di Roma (UNIROMA1)

Reference person: Alessandro De Luca <deluca@diag.uniroma1.it>

Name	Teacher	Ore	Class description	Availab le online	Time of the year (please check)	Langu age	Final evaluation	Level
Least Squares optimization on Factor Graphs, an overview	Giorgio Grisetti, Barbara Bazzana, Luca di Giammarino	20	Factor Graphs are graphical models that can represent a wide range of problems including, but not limited to SLAM, Visual and Lidar Odometry, Calibration, Structure from Motion, and Model Predictive Control. Effective methods to solve factor graphs are nowadays available. The aim of this course is to provide the students with a basic background on the formalism and on the techniques that can be used to solve these models. We plan to present several worked out examples, with small projects covering: Calibration, Point-Cloud Registration and Pose-Graph Optimization. https://sites.google.com/diag.uniroma1.it/onfactorgraphs/home	yes	May 2025	English	yes	ADVANCED
An introduction to PDEs and their applications in robotics	Andrea Cristofaro, Marilena Vendittelli	16	The scope of the course is to provide the basic knowledge to handle dynamical systems characterized by spatial distributed phenomena and governed by partial differential equations. After reviewing the needed theoretical background material, stability analysis and control design tools will be illustrated. Finally, in the second part of the course, applications to robotics and biomedical engineering will be considered, such as manipulation of flexible	yes	18-29 November 2024	English	yes	ADVANCED

materials or control of heat transfer in		
organic tissues.		

Università degli Studi di Siena (UNISI)

Reference person: Domenico Prattichizzo <dprattichizzo@unisi.it>

The courses can be BASIC (to establish cultural foundations), ADVANCED (advanced study of specific topics), CROSSOVER (on interdisciplinary subjects).

To be defined

Università degli Studi di Trento (UNITN)

Reference person: Daniele Fontanelli luigi.palopoli@unitn.it Luigi Palopoli Daniele Fontanelli <daniele.fontanelli@unitn.it>

Name	Teacher	Ore	Class description	Availab	Time of the	Langu	Final	Level
				le	year (please	age	evaluation	
				online	check)			
Fundamentals of	Daniele	18	The course provides an overview of	No	First or	English	The final	BASIC
statistical estimation	Fontanelli,		estimation algorithms that are most		second week		exam	
theory	daniele.font		commonly applied in engineering		of September		consists of a	
	anelli@unit		problems. The course will improve the		2025		multiple-	
	n.it		background knowledge to model, analyse				choice test	
			and solve estimation problems. The course				or a project	
			has theory and practical sections, mainly				for the intere	
			simulative. Depending on the availability of				sted	
			actual components, practical examples on				students.	
			actual software/hardware solutions are					
			foreseen.					
			The course covers the following topics:					
			- Background on stochastic processes and					
			random variables					
			- Minimum Variance Unbiased Estimators					
			- Cramer-Rao lower bound					
			- Best linear unbiased estimator					
			- Maximum Likelihood estimation					
			- Weighted least squares solutions					
			- Bayesian estimators					
			All the treated topics will be given with					
			examples and hands-on problems.					
Legged Robot Control	Andrea Del	12	The course provides an overview of state-	yes	July 2025	English	Students are	BASIC
	Prete,		of-the-art techniques for the dynamic				requires to	
	andrea.delp		control of robotic systems, with a specific				write a	
	rete@unitn.i		focus on legged robots (bipeds and				report,	
	t		quadrupeds). The course covers both				which is	
			theory and implementation, relying on the				evaluated	
			Python language and some existing				with pass/no	
			libraries for robot visualization, multi-body				pass.	

			dynamic computation, and trajectory optimization.					
Robot learning from demonstration	Matteo Saveriano, matteo.save riano@unitn .it	20	The course provides an overview of state-of-the-art approaches for robot learning from human demonstration. The course will focus on approaches that allow the robot to learn stable (in the sense of Lyapunov) discrete (point-to-point) and periodic (limit cycle) trajectories evolving in the Euclidean space. We then move to more complex space structures and introduce the concept of Riemannian manifold with a special focus on orientation and symmetric and positive definite matrices that are of interest in robotics. The presented mathematical tools will be then used to perform learning of motion patterns evolving on Riemannian manifolds. The course covers both theory and implementation of presented algorithms relying on existing, open-source implementations.	yes	September 2025	English	Project and report	BASIC
Factor Graphs for SLAM	Marco Camurri, marco.camu rri@unitn.it	18	The course wil introduce factor graphs as a general tool to solve optimization problems and how to apply them to robot perception, with particular application to Simultaneous Localization and Mapping (SLAM) and other correlated problems such as path planning	Yes	First two weeks of June 2025	English	Oral Examination	ADVANCED

Università della Calabria (UNICAL)

Reference person: Giuseppe Carbone <giuseppe.carbone@unical.it>

Name	Teacher	Ore	Class description	Availabl e online	Time of the year (please check)	Langua ge	Final evaluation	Level
Advanced scientific programming applied to process optimization using Matlab	Alessio Caravella, alessio.carav ella@unical. it	16	The course deals with parametric optimization of processes of interest for engineers. In particular, the Students will acquire the ability of formalizing and solve problems dealing with minimization of objective functions depending on parameters to optimize. For this purpose, the commercial software MATLAB® will be used.	Ask the teacher	Jan/Feb 2025	English	No	ADVANCED
Introduction to stochastic and mathematical modelling of discrete systems	Vittorio Astarita, vittorio.asta rita@unical.i t	12	The course begins with some introduction to probability theory and its applications to engineering problems. This will provide the foundation for the subsequent discussion of Markov chains. The course will then focus on the theory of Markov chains, including their definition, properties, and applications. Students will learn about discrete-time Markov chains and continuous-time Markov chains, as well as methods for analyzing these chains, such as the stationary distribution, and the limiting behavior of Markov chains. The course will also cover game theory and its application to engineering problems. Students will learn about the basics of game theory, including the concept of Nash equilibrium. In addition, the course will introduce students to the Monte Carlo method, a powerful tool for solving complex engineering problems. Students will learn how to simulate random events using	Ask the teacher	Feb 2025	English	No	BASIC

			Monte Carlo simulations and will apply this technique to a range of problems. Finally, the course will introduce students to Blockchain systems and digital currencies. Students will learn about the basics of Blockchain technology, including distributed ledgers and smart contracts, and will explore the potential applications of this technology to engineering problems. Throughout the course, students will be exposed to representative case studies that demonstrate the application of the aforementioned theories to real-world engineering problems. By the end of the course, students will have a better understanding of probability theory and its applications to engineering, as well as a					
			general view on practical toolkits for					
			solving complex engineering problems.					
How to conduct a	Vittorio Astarita, vittorio.asta rita@unical.i t	12	This course is designed to provide an introduction to the fundamental concepts of the Python programming language. Students will learn the syntax and semantics of Python, including variables, data types, and control structures. The course will cover basic data structures such as lists, dictionaries, and tuples, as well as functions and modules. Students will also learn about file input/output, error handling, and debugging techniques. By the end of the course, students will have gained a solid foundation in Python programming, which they can use to solve real-world problems.	Ask the	Feb/Mar 2025	English	No	CROSSOVER
How to conduct a Systematic Literature Review: design, methods and supporting tools	Salvatore Ammirato, Marilena De Simone salvatore.a mmirato@u nical.it, marilena.de	8	Topics: Motivation and goals of a systematic literature review (SLR); Methodology; Literature search, Exclusion and inclusion criteria, Metadata Analysis, Synthesis and results presentation. Applications: Designing a SLR; Paper location and selection; Paper analysis; Results synthesis; Digital tools for SLR; The	Ask the teacher	Nov/Dec 2024	English	No	CROSSOVER

	simone@uni		MySLR digital platform; How to conduct a					
	cal.it		review with MySLR; Project works					
Spin-off creation: key	Gianpaolo	8	The course describes the main steps for	Ask the	May 2025	English	No	CROSSOVER
fundamentals for a good	lazzolino,		constructing a business plan also referred	teacher				
plan	gianpaolo.ia		to projects arising from results obtained in					
	zzolino@uni		research. The main areas of a business plan					
	cal.it		are described with reference to the s.c.					
			technology firms. The course proposes					
			insights deriving from cases of spin-offs at					
			the University of Calabria					

Università Politecnica delle Marche (UNIVPM)

Reference person: Massimo Callegari <m.callegari@univpm.it>, David Scaradozzi <d.scaradozzi@univpm.it>
The courses can be BASIC (to establish cultural foundations), ADVANCED (advanced study of specific topics), CROSSOVER (on interdisciplinary subjects).

Name Tea	Teacher	Ore	Class description	Availab le	Time of the year (please	Langu age	Final evaluation	Level
				online	check)	age	evaluation	
Design of research: European Projects	Nicola Paone, n.paone@un ivpm.it	24	 Introduction to instruments and funding agencies for research. European research European research European frame-work programmes and Horizon Europe Financial instruments in support of research. The role of industry in framework programmes. Technology platforms. Steps in project proposal preparation analysis of Call for Proposals and Workprogramme definition of objectives definition of partnership definition of impact the work-programme state of art budget and resources Project proposal evaluation Marie Curie actions for mobility of researchers Project management, progress and scientific reporting. (Project meeting, deliverables, reports, etc.) Administrative/financial management: financial reporting audit Examples of projects. Tutorial sessions. 	yes	Jan/Feb 2025	English	yes	CROSSOVER

Tools and methods for process representation and management	Ferruccio Mandorli, f.mandorli@ univpm.it	24	Formal tools for process representation: definition of IDEFO diagrams and their use for the AS-IS and TO-BE representation of processes; definition of IDEF3 diagrams for the representation of sequences of tasks; definition of Gantt diagrams for task planning and resources allocation. Process management tools: introduction to Microsoft Project; basic concepts; definition of the tasks planning; resources allocation; assessment of the scheduling of the tasks. Data elaboration tools: advanced use of Excel; advanced query and selection functions; advanced filters; pivot tables; how to use the solver; introduction to the VBA framework for macro development and use of ActiveX controls. Tools for data storing, query and presentation: brief introduction to MS Access and MS Visio.	yes (also e- learning)	Jan/Feb 2025	English	yes	CROSSOVER
Project management techniques	Filippo Ciarapica, f.e.ciarapica @univpm.it	24	Understanding Project Life Cycle and Project Portfolio Management Processes. Project Scope Management. WBS: creating the Work Breakdown Structure. Resource planning and estimating. Time estimating techniques. Cost estimating techniques. Project Business Plan. Risk management planning: qualitative and quantitative risk analysis.	yes	Jan/Feb 2025	English	yes	CROSSOVER
Virtual instruments (LabView) for monitoring and management of industrial systems	Milena Martarelli, m.martarelli @univpm.it	24	 General approach to G programming Troubleshooting and debug Implementation of a virtual instrument Development of modular applications Arrays Hardware e software resources Data Acquisition Data Flow 	yes	Jan/Feb 2025	English	yes	BASIC

Mathematical	Fabrizio	24	Decision Problems	yes	Mar/Apr 2025	English	yes	ADVANCED
programming and graph	Marinelli,	- '	Elements and taxonomy	,	a.,,,,pi 2023		,55	
theory	fabrizio.mari		 Solution of a decision problem 					
,	nelli@staff.u		 Easy and hard problems, exact 					
	nivpm.it		and heuristic algorithms: hints of					
			computational complexity theory					
			 Multi-objective problems: goal 					
			programming and pareto-					
			optimality					
			Mathematical Programming					
			 Declarative languages: AMPL 					
			 Decision problems and math. 					
			prog.					
			 Integer Linear Programming: 					
			features and solution methods					
			Modelling techniques					
			binary variables for selection:					
			covering, packing and partitioning					
			models					
			 binary variables for association: 					
			assignments and permutations.					
			Logic variables: fixed costs, semi-					
			continuous sets, conditional					
			constraints, logical predicates					
			 Linearization techniques: absolute values, piecewise linear 					
			functions, exponential functions					
			runctions, exponential functions					
			An introduction to Graph Theory					
			 Terminology and basic properties 					
			 Isomorphisms and classes of 					
			graphs: paths, cycles, trees,					
			eulerian, hamiltonian, bipartite					
			and planar graphs					
			Independent sets and covers			1		
			Greedy algorithm and matroids Greeting and Continuous and					
			Combinatorial Optimization and			1		
			graphs			1		
			Mathematical prog. for Aprimization problems on graphs.					
			optimization problems on graphs			1		
						l		

	Applications			
	 Scheduling, routing and packing 			
	problems			

Università Cattolica Milano (UNICATT)

Reference person: Antonella Marchetti <antonella.marchetti@unicatt.it>

Name	Teacher	Ore	Class description	Availab le online	Time of the year (please check)	Langu age	Final evaluation	Level
Developing In Human-Robot Interaction	Antonella Marchetti, Cinzia Di Dio, Federico Manzi & Giulia Peretti, antonella.ma rchetti@unic att.it	16	Social robots represent the new frontier of interactions. We are looking at a future in which these entities will be included and integrated within many types of everyday activities, where they will be our new friends, collaborators, educators, and care assistants. In this course we will therefore offer a look at the state of the art in the development of robots as socially effective agents in psychology, highlighting their strengths, and trying to project our thinking into a future where these entities can be perceived as social partners. We will approach to the main psychological developmental steps in early infancy (e.g., gaze, imitation, action understanding), embodied cognition, social cognition (i.e., Theory of Mind) with respect to social and educational robotics. These will help to better understand the role of developmental psychology in Al and Human-Robot Interaction.	yes	June/July 2025	English	yes	BASIC