



Ph.D COURSE ROBOTICS AND INTELLIGENT MACHINES CURRICULUM HOSTILE AND UNSTRUCTURED ENVIRONMENTS (CODICE 12190), XLII CICLO

Following the assessment of qualifications (Step 1), the below candidates:

Cognome	Nome	Totale /60	Tema di ricerca con priorità 1	Tema di ricerca con priorità 2	Tema di ricerca con priorità 3
BORGHI	GAIA	55	SLAM FOR LEGGED ROBOTS IN DYNAMICALLY CHANGING ENVIRONMENTS – ITALIAN INSTITUTE OF TECHNOLOGY		
GAY	CAROLINA	55	HIGHLY INTEGRATED OPTICAL SENSORS IN SOFT ROBOTIC MANIPULATORS – ITALIAN INSTITUTE OF TECHNOLOGY		
GAMAHDRID IUALE'	AMIR	50	DESIGNING AND DEVELOPING HUMANOID ROBOT COMPANIONS – UNIVERSITY OF GENOVA	SLAM FOR LEGGED ROBOTS IN DYNAMICALLY CHANGING ENVIRONMENTS – ITALIAN INSTITUTE OF TECHNOLOGY	
GAO	XINYU	50	DESIGNING AND DEVELOPING HUMANOID ROBOT COMPANIONS – UNIVERSITY OF GENOVA	DESIGN AND CONTROL OF MODULAR ROBOTIC END-SYSTEMS FOR DEFORMABLE OBJECT MANIPULATION – ITALIAN INSTITUTE OF TECHNOLOGY	SLAM FOR LEGGED ROBOTS IN DYNAMICALLY CHANGING ENVIRONMENTS – ITALIAN INSTITUTE OF TECHNOLOGY
MOUDALLAL	MOHAMAD SAID	50	CO-DESIGN OF INNOVATIVE MECHANISMS AND QUADRUPED LOCOMANIPULATION THROUGH REINFORCEMENT LEARNING - ITALIAN INSTITUTE OF TECHNOLOGY		

DELLI CARRI	EUGENIO	49	DESIGNING AND DEVELOPING HUMANOID ROBOT COMPANIONS – UNIVERSITY OF GENOVA	SLAM FOR LEGGED ROBOTS IN DYNAMICALLY CHANGING ENVIRONMENTS – ITALIAN INSTITUTE OF TECHNOLOGY	DESIGN AND CONTROL OF MODULAR ROBOTIC END-SYSTEMS FOR DEFORMABLE OBJECT MANIPULATION – ITALIAN INSTITUTE OF TECHNOLOGY
ANDREOTTI	MICHELA	48	PERCEPTION-DRIVEN TASK-PRIORITY CONTROL FOR UNDERWATER INTERVENTION ROBOTIC – UNIVERSITY OF GENOVA	DESIGNING AND DEVELOPING HUMANOID ROBOT COMPANIONS – UNIVERSITY OF GENOVA	
ANDREUCCI	FILIPPO	46	HIGHLY INTEGRATED OPTICAL SENSORS IN SOFT ROBOTIC MANIPULATORS – ITALIAN INSTITUTE OF TECHNOLOGY	DESIGN AND CONTROL OF MODULAR ROBOTIC END-SYSTEMS FOR DEFORMABLE OBJECT MANIPULATION – ITALIAN INSTITUTE OF TECHNOLOGY	
CONNOLLY	SAMANTHA	46	PERCEPTION-DRIVEN TASK-PRIORITY CONTROL FOR UNDERWATER INTERVENTION ROBOTIC – UNIVERSITY OF GENOVA	DISTRIBUTED AUTONOMY AND INTELLIGENT NAVIGATION FOR SERIOUS GAMES WITH BIOMIMETIC ROBOT SWARMS IN GNSS-DENIED ENVIRONMENTS – MARCHE POLYTECHNIC UNIVERSITY	
ELGABALAWY	MAZEN AYMAN SALAH ELDIN SAYED	46	PERCEPTION-DRIVEN TASK-PRIORITY CONTROL FOR UNDERWATER INTERVENTION ROBOTIC – UNIVERSITY OF GENOVA	SLAM FOR LEGGED ROBOTS IN DYNAMICALLY CHANGING ENVIRONMENTS – ITALIAN INSTITUTE OF TECHNOLOGY	
MAGNO	FRANCESCA	44	DESIGNING AND DEVELOPING HUMANOID ROBOT COMPANIONS – UNIVERSITY OF GENOVA		
PRAMUDYA	MUHAMMAD AZKA BINTANG	44	PERCEPTION-DRIVEN TASK-PRIORITY CONTROL FOR UNDERWATER INTERVENTION ROBOTIC – UNIVERSITY OF GENOVA	DISTRIBUTED AUTONOMY AND INTELLIGENT NAVIGATION FOR SERIOUS GAMES WITH BIOMIMETIC ROBOT SWARMS IN GNSS-DENIED ENVIRONMENTS – MARCHE POLYTECHNIC UNIVERSITY	

TROVALUSCI	SERENA	44	DESIGN AND CONTROL OF MODULAR ROBOTIC END-SYSTEMS FOR DEFORMABLE OBJECT MANIPULATION – ITALIAN INSTITUTE OF TECHNOLOGY	HIGHLY INTEGRATED OPTICAL SENSORS IN SOFT ROBOTIC MANIPULATORS – ITALIAN INSTITUTE OF TECHNOLOGY	
ANDREINI	MATTIA	43	SLAM FOR LEGGED ROBOTS IN DYNAMICALLY CHANGING ENVIRONMENTS – ITALIAN INSTITUTE OF TECHNOLOGY	CO-DESIGN OF INNOVATIVE MECHANISMS AND QUADRUPEL LOCOMOTION THROUGH REINFORCEMENT LEARNING - ITALIAN INSTITUTE OF TECHNOLOGY	DESIGN AND CONTROL OF MODULAR ROBOTIC END-SYSTEMS FOR DEFORMABLE OBJECT MANIPULATION - ITALIAN INSTITUTE OF TECHNOLOGY
ALINAGHIAN	MOBINA	42	CO-DESIGN OF INNOVATIVE MECHANISMS AND QUADRUPEL LOCOMOTION THROUGH REINFORCEMENT LEARNING - ITALIAN INSTITUTE OF TECHNOLOGY	SLAM FOR LEGGED ROBOTS IN DYNAMICALLY CHANGING ENVIRONMENTS – ITALIAN INSTITUTE OF TECHNOLOGY	DESIGNING AND DEVELOPING HUMANOID ROBOT COMPANIONS – UNIVERSITY OF GENOVA
ARGHIDEH	SAYNA	42	DESIGN AND CONTROL OF MODULAR ROBOTIC END-SYSTEMS FOR DEFORMABLE OBJECT MANIPULATION – ITALIAN INSTITUTE OF TECHNOLOGY		
JOSHI	ABHINAV	42	CO-DESIGN OF INNOVATIVE MECHANISMS AND QUADRUPEL LOCOMOTION THROUGH REINFORCEMENT LEARNING - ITALIAN INSTITUTE OF TECHNOLOGY	DESIGNING AND DEVELOPING HUMANOID ROBOT COMPANIONS – UNIVERSITY OF GENOVA	SLAM FOR LEGGED ROBOTS IN DYNAMICALLY CHANGING ENVIRONMENTS – ITALIAN INSTITUTE OF TECHNOLOGY
MISHRA	RAHUL	40	SLAM FOR LEGGED ROBOTS IN DYNAMICALLY CHANGING ENVIRONMENTS – ITALIAN INSTITUTE OF TECHNOLOGY		

are invited to the online interview (Step 2 - oral examination) on FRIDAY 24th July 2026 at 9.30 (Central European Summer Time) through the Teams call:

<https://teams.microsoft.com/meet/317756929690451?p=swpxCyyH7fMDpR47tH>

If you have problems connecting, please feel free to contact Prof. Antonio Sgorbissa at +39 320 4218938 or at antonio.sgorbissa@unige.it

Candidates will be required to exhibit a valid identification document prior to starting the interview.