



Ph.D COURSE ROBOTICS AND INTELLIGENT MACHINES CURRICULUM INDUSTRY 4.0 (CODICE 12191) XLII CICLO

The following rankings are unofficial. The official results will be published on the University website <https://unige.it/en/students/phd-programmes>.

The enrollments will start as detailed in the call. Considering the individual scores assigned for the evaluation of qualifications and the interview, the Commission prepares the following ranking for each research topic.

1. MULTI-AGENT COGNITIVE ARCHITECTURES FOR HETEROGENEOUS ROBOT COORDINATION ACROSS DIFFERENT EMBODIMENTS – FUSION ALLABS S.r.l.

DATTA	AHANA	111	su 120*
GALVAGNI	GIANLUCA	110	su 120*
KHAN	ZAHRA	94	su 120*
MOJTAHEDI	REZA	91	su 120*

2. TASK AND MOTION PLANNING MODELS FOR COGNITIVE ROBOTS – UNIVERSITY OF GENOVA

DATTA	AHANA	111	su 120*
GALVAGNI	GIANLUCA	110	su 120*
KHAN	ZAHRA	94	su 120*
HAULOOMAN	HITISH	92	su 120*
MOJTAHEDI	REZA	91	su 120*
DELLI CARRI	EUGENIO	90	su 120*
UDDIN	SYED ZIA	86	su 120*

3. SENSING, PERCEPTION AND CONTROL FOR HUMAN-ROBOT PHYSICAL INTERACTION – UNIVERSITY OF GENOVA

BONO	ALBERTO	108	su 120*
BERDINI	EMANUELE	101	su 120*
DELLI CARRI	EUGENIO	96	su 120*

4. DESIGN AND VIRTUAL PROTOTYPING OF ROBOT HANDS FOR HUMANOIDS – UNIVERSITY OF GENOVA (MUR/DIME)

PRESTANA	RICCARDO	100	su 120*
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5. MULTIMODAL AI FOR GENERATING ANTICIPATORY ROBOT BEHAVIORS THAT ADAPT TO PHYSICAL AND COGNITIVE ERGONOMICS AND HUMAN INTENTIONS - ITALIAN INSTITUTE OF TECHNOLOGY

RABIEI	MILAD	101	su 120*
ZHANG	JING	99	su 120*
VATANKHAHAN	MAHDY	94	su 120*
SQUITIERI	BENIAMINO	93	su 120*

6. PHYSICAL AI AND HUMANOID ROBOTICS FOR ADAPTIVE INDUSTRIAL PRODUCTION SYSTEMS – ITALIAN INSTITUTE OF TECHNOLOGY (N. 2 POSITIONS)

AJMAR	CAROLA	110	su 120*
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GIORDANO	MATTIA	106	su 120*
ARGHIDEH	SAYNA	104	su 120*
CALUGI	GIANPIETRO	96	su 120*

7. VISION-LANGUAGE-ACTION INTELLIGENCE FOR RESILIENT MULTI-ROBOT CONSTRUCTION - ITALIAN INSTITUTE OF TECHNOLOGY

GAO	XINYU	104	su 120*
RABIEI	MILAD	101	su 120*
SQUITIERI	BENIAMINO	93	su 120*
HU	DONGNAN	87	su 120*

8. FOUNDATION MODELS FOR HUMAN-ROBOT COLLABORATION AND TACTILE MANIPULATION – UNIVERSITY OF CAMPANIA “LUIGI VANVITELLI”

CHIARIELLO	CLAUDIO	110	su 120*
HAULOOMAN	HITISH	85	su 120*

9. DEVELOPMENT AND INTEGRATION OF HAPTIC DEVICES FOR EXTENDED REALITY APPLICATIONS - UNIVERSITY OF SIENA

PIDATELLA	MARZIA	102	su 120*
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10. GENERATIVE PHYSICAL AI FOR HUMANOID ROBOTICS WITH DIFFERENTIABLE COMPUTATIONAL MODELS - GENERATIVE BOINICS BIONICS S.r.l.

BORGHERINI	ALESSANDRO	101	su 120*
GIANFORCARO	LUCA	96	su 120*

11. INTELLIGENT LOCO-MANIPULATION PLANNING AND CONTROL OF MOBILE ROBOTS – LEONARDO S.p.A

ALBONI	ANDREA	111	su 120*
BERDINI	EMANUELE	107	su 120*
ANDREINI	MATTIA	102	su 120*

12. OPTIMIZATION OF FLEXIBLE ROBOTIC WORK-CELL FOR INDUSTRIAL HANDLING - place reserved for INNOVA S.r.l. employee

KOVACHEV	ZLATKO	100	su 120*
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